

DOMÁ ÚLOHA ① - ROBERTA JURÍKOVÁ

Nájdite maticu ortog. projekcie na podpriestor $S \subseteq \mathbb{R}^4$

$$\begin{aligned} \vec{e}_1 &= d_1 \vec{u}_1 + d_2 \vec{u}_2 + d_3 \vec{u}_3 \\ \vec{e}_2 &= \beta_1 \vec{u}_1 + \beta_2 \vec{u}_2 + \beta_3 \vec{u}_3 \\ \vec{e}_3 &= \gamma_1 \vec{u}_1 + \gamma_2 \vec{u}_2 + \gamma_3 \vec{u}_3 \\ \vec{e}_4 &= \delta_1 \vec{u}_1 + \delta_2 \vec{u}_2 + \delta_3 \vec{u}_3 \end{aligned}$$

≡

$$\begin{aligned} \vec{e}_1 - f(\vec{e}_1) & \perp \vec{u}_1 \Rightarrow \langle \vec{e}_1 - f(\vec{e}_1), \vec{u}_1 \rangle = 0 \Rightarrow \langle f(\vec{e}_1), \vec{u}_1 \rangle = \langle \vec{e}_1, \vec{u}_1 \rangle \\ \vec{e}_1 - f(\vec{e}_1) & \perp \vec{u}_2 \Rightarrow \langle \vec{e}_1 - f(\vec{e}_1), \vec{u}_2 \rangle = 0 \Rightarrow \langle f(\vec{e}_1), \vec{u}_2 \rangle = \langle \vec{e}_1, \vec{u}_2 \rangle \\ \vec{e}_1 - f(\vec{e}_1) & \perp \vec{u}_3 \Rightarrow \langle \vec{e}_1 - f(\vec{e}_1), \vec{u}_3 \rangle = 0 \Rightarrow \langle f(\vec{e}_1), \vec{u}_3 \rangle = \langle \vec{e}_1, \vec{u}_3 \rangle \end{aligned}$$

pre $i=1$: neznáme: d_1, d_2, d_3

$$S = [\underbrace{(1, -1, 2, 0)}_{\vec{u}_1}, \underbrace{(0, 1, -1, -1)}_{\vec{u}_2}, \underbrace{(0, 1, -3, 1)}_{\vec{u}_3}]$$

$$\langle f(\vec{e}_1), \vec{u}_1 \rangle = \langle \vec{e}_1, \vec{u}_1 \rangle$$

$$\langle d_1 \vec{u}_1 + d_2 \vec{u}_2 + d_3 \vec{u}_3, \vec{u}_1 \rangle = d_1 \langle \vec{u}_1, \vec{u}_1 \rangle + d_2 \langle \vec{u}_2, \vec{u}_1 \rangle + d_3 \langle \vec{u}_3, \vec{u}_1 \rangle = \langle \vec{e}_1, \vec{u}_1 \rangle$$

$$\langle f(\vec{e}_1), \vec{u}_2 \rangle = d_1 \langle \vec{u}_1, \vec{u}_2 \rangle + d_2 \langle \vec{u}_2, \vec{u}_2 \rangle + d_3 \langle \vec{u}_3, \vec{u}_2 \rangle = \langle \vec{e}_1, \vec{u}_2 \rangle$$

$$\langle f(\vec{e}_1), \vec{u}_3 \rangle = d_1 \langle \vec{u}_1, \vec{u}_3 \rangle + d_2 \langle \vec{u}_2, \vec{u}_3 \rangle + d_3 \langle \vec{u}_3, \vec{u}_3 \rangle = \langle \vec{e}_1, \vec{u}_3 \rangle$$

rovnako platí aj pre $i=2, 3, 4$. Ľavé strany sa nemenia, menia sa iba neznáme a pravé strany, preto budeme riešiť 4 lineárne systémy rovníc.

$\langle \vec{u}_1, \vec{u}_1 \rangle$	$\langle \vec{u}_2, \vec{u}_1 \rangle$	$\langle \vec{u}_3, \vec{u}_1 \rangle$	$\langle \vec{e}_1, \vec{u}_1 \rangle$	$\langle \vec{e}_2, \vec{u}_1 \rangle$	$\langle \vec{e}_3, \vec{u}_1 \rangle$	$\langle \vec{e}_4, \vec{u}_1 \rangle$
$\langle \vec{u}_1, \vec{u}_2 \rangle$	$\langle \vec{u}_2, \vec{u}_2 \rangle$	$\langle \vec{u}_3, \vec{u}_2 \rangle$	$\langle \vec{e}_1, \vec{u}_2 \rangle$	$\langle \vec{e}_2, \vec{u}_2 \rangle$	$\langle \vec{e}_3, \vec{u}_2 \rangle$	$\langle \vec{e}_4, \vec{u}_2 \rangle$
$\langle \vec{u}_1, \vec{u}_3 \rangle$	$\langle \vec{u}_2, \vec{u}_3 \rangle$	$\langle \vec{u}_3, \vec{u}_3 \rangle$	$\langle \vec{e}_1, \vec{u}_3 \rangle$	$\langle \vec{e}_2, \vec{u}_3 \rangle$	$\langle \vec{e}_3, \vec{u}_3 \rangle$	$\langle \vec{e}_4, \vec{u}_3 \rangle$
			$\uparrow d_1$	$\uparrow \beta_i$	$\uparrow \gamma_i$	$\uparrow \delta_i$

$$\begin{aligned} & \left(\begin{array}{ccc|ccc} 6 & -3 & -7 & 1 & -1 & 2 & 0 \\ -3 & 3 & +3 & 0 & 1 & -1 & 0 \\ -7 & +3 & 11 & 0 & 1 & -3 & 1 \end{array} \right) \xrightarrow{2 \cdot R_1 + R_2} \left(\begin{array}{ccc|ccc} 6 & -3 & -7 & 1 & -1 & 2 & 0 \\ -3 & 3 & -3 & 0 & 1 & -1 & 0 \\ -7 & +3 & 11 & 0 & 1 & -3 & 1 \end{array} \right) \sim \\ & \left(\begin{array}{ccc|ccc} 1 & 6 & -4 & -1 & 0 & 1 & -1 \\ 0 & 3 & -13 & 1 & 1 & 0 & 0 \\ -3 & 3 & -3 & 0 & 1 & -1 & 0 \end{array} \right) \xrightarrow{3 \cdot R_1 + R_2} \left(\begin{array}{ccc|ccc} 1 & 6 & -4 & -1 & 0 & 1 & -1 \\ 0 & 1 & -13 & 1 & 1 & 0 & 0 \\ 0 & 21 & -15 & -3 & 1 & 2 & -3 \end{array} \right) \xrightarrow{21 \cdot R_2 - R_3} \left(\begin{array}{ccc|ccc} 1 & 6 & -4 & -1 & 0 & 1 & -1 \\ 0 & 1 & -13 & 1 & 1 & 0 & 0 \\ 0 & 7 & -5 & -1 & \frac{1}{3} & \frac{2}{3} & -1 \end{array} \right) \\ & \left(\begin{array}{ccc|ccc} 1 & 6 & -4 & -1 & 0 & 1 & -1 \\ 0 & 1 & -13 & 1 & 1 & 0 & 0 \\ 0 & 0 & 86 & 0 & 0 & 0 & 0 \end{array} \right) \end{aligned}$$

$$\begin{pmatrix} 6 & -3 & -7 & 1 & -1 & 2 & 0 \\ -3 & 3 & 3 & 0 & 1 & -1 & 1 \\ -7 & 3 & 11 & 0 & 1 & -3 & 1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} -3 & 3 & 3 & 0 & 1 & -1 & 1 \\ 6 & -3 & -7 & 1 & -1 & 2 & 0 \\ -7 & 3 & 11 & 0 & 1 & -3 & 1 \end{pmatrix} \xrightarrow{R_1 \cdot (-1/3)} \begin{pmatrix} 1 & -1 & -1 & 0 & -1/3 & 1/3 & -1/3 \\ 6 & -3 & -7 & 1 & -1 & 2 & 0 \\ -7 & 3 & 11 & 0 & 1 & -3 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 & -1 & 0 & -1/3 & 1/3 & -1/3 \\ 6 & -3 & -7 & 1 & -1 & 2 & 0 \\ -7 & 3 & 11 & 0 & 1 & -3 & 1 \end{pmatrix} \xrightarrow{R_2 - 6R_1, R_3 + 7R_1} \begin{pmatrix} 1 & -1 & -1 & 0 & -1/3 & 1/3 & -1/3 \\ 0 & 3 & -1 & 1 & 1 & 0 & 2 \\ 0 & 0 & -8 & 0 & 2 & -2 & -2 \end{pmatrix} \xrightarrow{R_2 \cdot 1/3} \begin{pmatrix} 1 & -1 & -1 & 0 & -1/3 & 1/3 & -1/3 \\ 0 & 1 & -1/3 & 1/3 & 1/3 & 0 & 2/3 \\ 0 & 0 & -8 & 0 & 2 & -2 & -2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & -1/3 & 1/3 & 1/3 & 0 & 2/3 \\ 0 & 0 & 1 & 1/2 & 0 & -1/4 & 1/4 \end{pmatrix} \xrightarrow{R_2 + 1/3 R_3} \begin{pmatrix} 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1/2 & 1/3 & -1/12 & 7/12 \\ 0 & 0 & 1 & 1/2 & 0 & -1/4 & 1/4 \end{pmatrix}$$

$\Rightarrow d_1 = 1 \quad d_2 = \frac{1}{2} \quad d_3 = \frac{1}{2}$
 $\Rightarrow \vec{e}_1 = (1, -1, 2, 0) + (0, \frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}) + (0, \frac{1}{2}, \frac{3}{2}, \frac{1}{2})$
 $\beta_1 = 0 \quad \beta_2 = \frac{1}{3} \quad \beta_3 = 0 \quad \vec{e}_2 = (0, \frac{1}{3}, -\frac{1}{3}, \frac{1}{3})$
 $\tau_1 = 0 \quad \tau_2 = -\frac{1}{12} \quad \tau_3 = -\frac{1}{4} \quad \vec{e}_3 = (0, -\frac{1}{12}, \frac{1}{12}, \frac{1}{12}) + (0, -\frac{1}{4}, \frac{3}{4}, -\frac{1}{4})$
 $\delta_1 = 0 \quad \delta_2 = -\frac{7}{12} \quad \delta_3 = \frac{1}{4} \quad \vec{e}_4 = (0, -\frac{7}{12}, \frac{7}{12}, \frac{7}{12}) + (0, \frac{1}{4}, -\frac{3}{4}, \frac{1}{4})$

$\Rightarrow \vec{e}_1 = (1, 0, 0, 0)$
 $\vec{e}_2 = (0, \frac{1}{3}, -\frac{1}{3}, \frac{1}{3})$
 $\vec{e}_3 = (0, -\frac{1}{3}, \frac{5}{6}, -\frac{1}{6})$
 $\vec{e}_4 = (0, -\frac{1}{3}, -\frac{1}{6}, \frac{5}{6})$

$\Rightarrow M_P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{3} & -\frac{1}{3} & -\frac{1}{3} \\ 0 & -\frac{1}{3} & \frac{5}{6} & -\frac{1}{6} \\ 0 & -\frac{1}{3} & -\frac{1}{6} & \frac{5}{6} \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 1 & -1 & -1 \\ 0 & -1 & \frac{5}{2} & -\frac{1}{2} \\ 0 & -1 & -\frac{1}{2} & \frac{5}{2} \end{pmatrix}$